## M&T Protocol Specification Ta-ext-RS485-MT / Tm-RS485-MT Tamb485-MT / Tmodul-MT / Tamb485-T-MT

This document describes the M&T protocol of the RS485 port of the sensors Ta-ext-RS485-MT, Tm-RS485-MT, Tamb485-MT, Tmodul-MT and Tamb485-T-MT, called "sensor".

The data logger or a control system has the function of the master, the senor has the function of the slave. The sensor address has a range of 00 to 99. The sensor address is specified by the last two signs of the serial number. Each sensor has a fixed, for the user not changeable address. Data format: 9600 baud, 8 data bits, no parity, one stop bit.

## Command structure:

Master	Sensor	Comment
#aa0 <cr></cr>	<lf>*aa7<cr></cr></lf>	Command for recognition
		a sensor
#aav <cr></cr>	<lf>*aavhhhsss<cr></cr></lf>	Command for requesting hardware and software version
#aa7 <cr></cr>	<lf>*aa7 <data1> <data 2=""> <crc><cr></cr></crc></data></data1></lf>	Command for data request

aa: Address of the sensor, defined by the last to signs of the serial number, setting by the manufacturer

0: Command for recognition a sensor

7: Command for data request

v: Command for requesting hardware and software version

hhh: Hardware Version sss: Software Version

data 1: Measurement value for cell temperature in [°C], field length: 5

data 2: Measurement value for ambient temperature in [°C], field length: 5

CRC: Addition of all characters before CRC without <LF> as integer U8. Attention: The CRC could contain non-printable-characters.

All measurement values contain a decimal separator (0x2e) and one decimal place. The field length includes the decimal separator. At measurement values with a smaller field length space characters are added. Each measurement value has at minimum one space character before and behind. So, each command and each request contains a fixed number of characters.

## Example Tamb485-MT with Bus address 01:

Master: #010<CR>
Slave: <LF>\*017 <CR>
Master: #01v<CR>

Slave: <LF>\*01v131108<CR>

Master: #017<CR>

Slave: <LF>\*017\_\_75.0\_\_18.1\_<CRC><CR> (space characters are displayed as \_)

To prevent collisions all sensors at the same bus must have different addresses.

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